

# COMPUTATION OF EXPLICIT PREIMAGES IN ONE-DIMENSIONAL CELLULAR AUTOMATA APPLYING THE DEBRUIJN DIAGRAM

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MÉXICO, CITY.

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- ☐ CELLULAR AUTOMATA
- ☐ THE DEBRUIJN GRAPH AND CELLULAR AUTOMATA



# ORIGIN OF THE DEBRUIJN DIAGRAM

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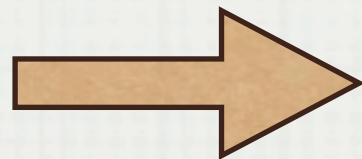
N. DEBRUIJN SOLVED THE PROBLEM OF  
FINDING A MINIMUM-LENGTH BINARY  
STRING THAT CONTAINS AS A  
SUBSTRING EVERY BINARY STRING OF A  
PRESCRIBED LENGTH  $k$ .

# EXAMPLE

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A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 0111010001





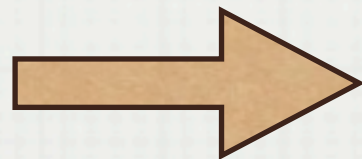
# EXAMPLE

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A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 011010001

011



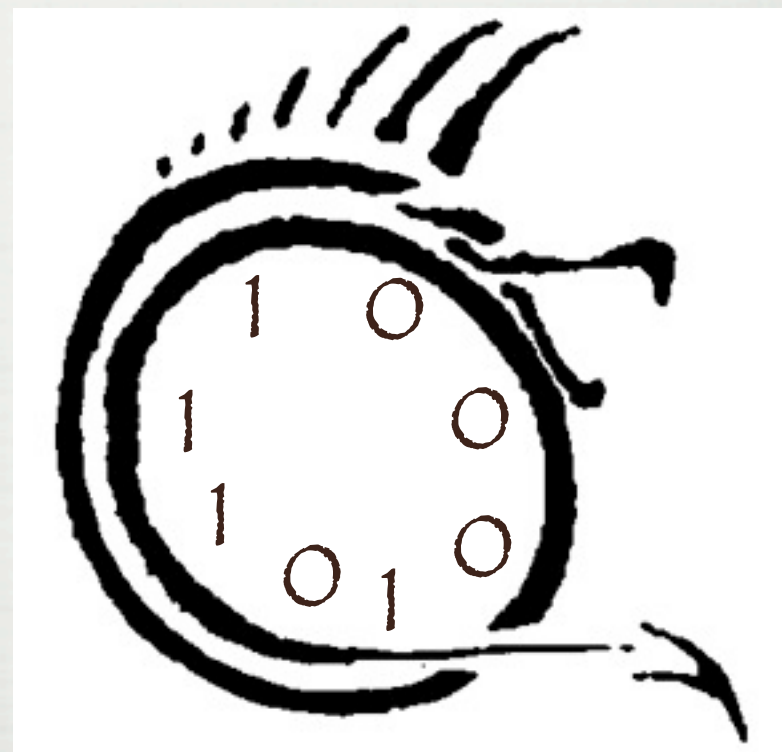
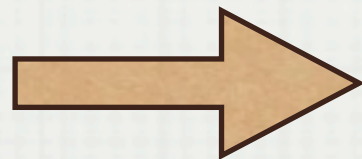
# EXAMPLE

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A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 0111010001

011  
111





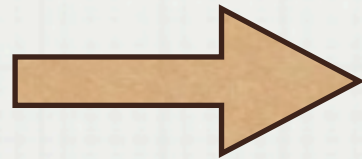
# EXAMPLE

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A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 0111010001

011  
111  
110



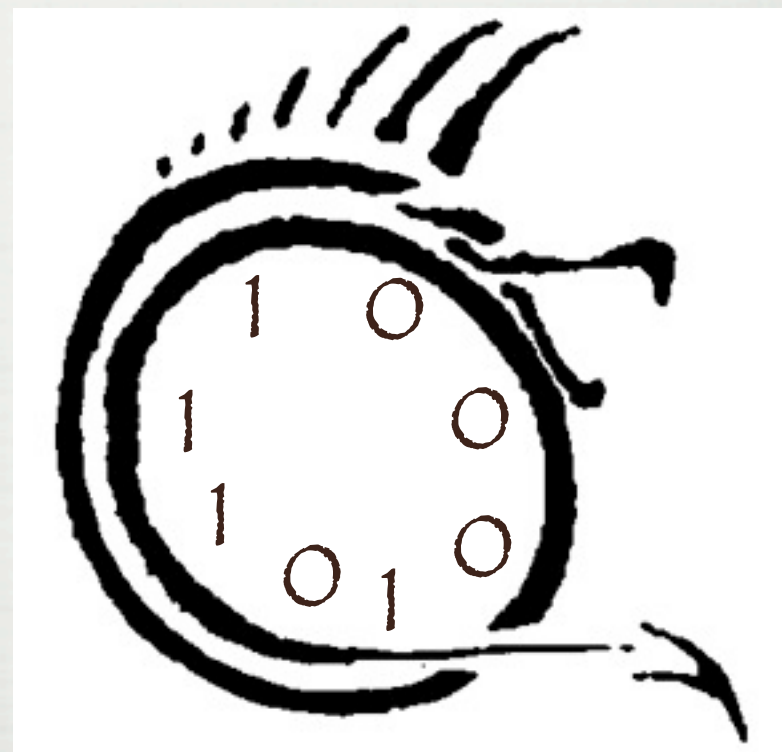
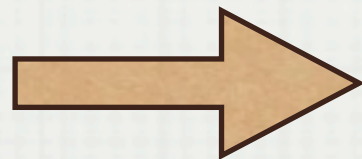
# EXAMPLE

---

A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 011010001

011  
111  
110  
101





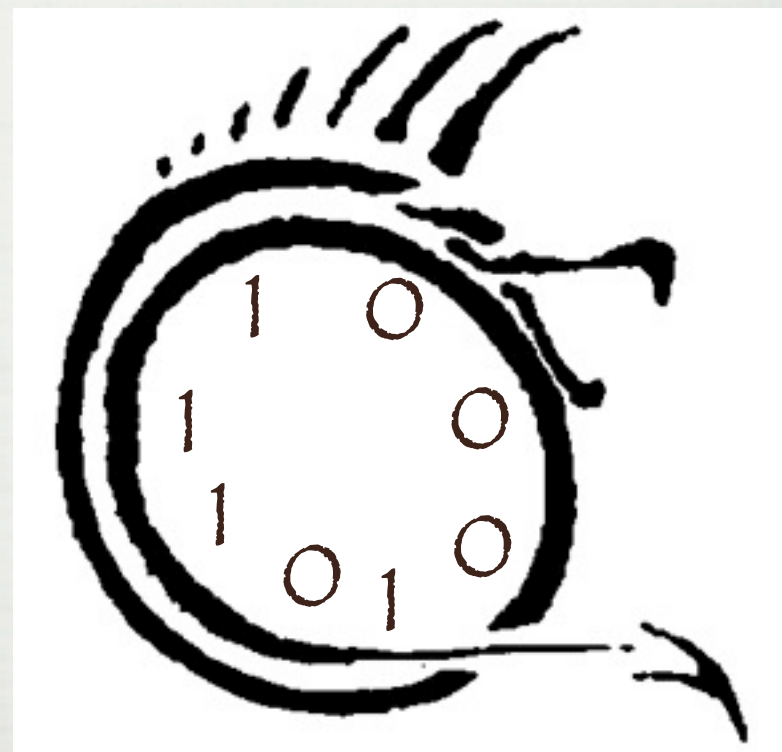
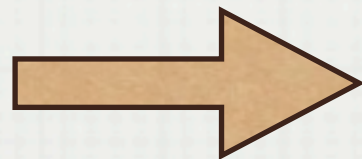
# EXAMPLE

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A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 0111010001

011  
111  
110  
101  
010

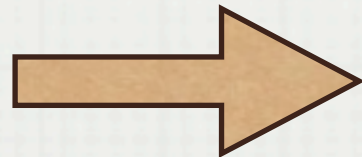


# EXAMPLE

A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 0111010001

011  
111  
110  
101  
010  
100



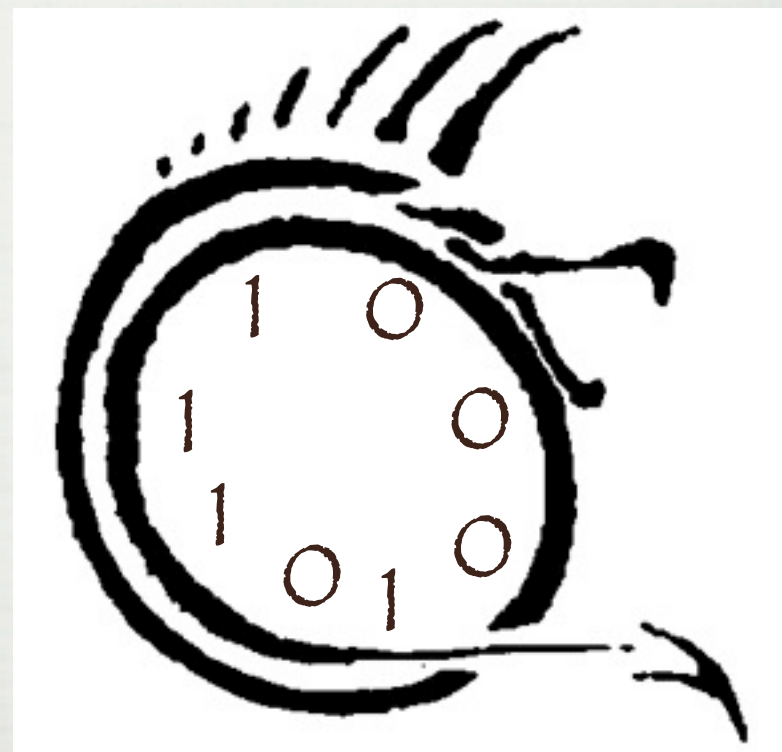
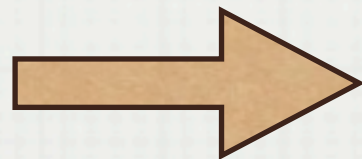


# EXAMPLE

A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 0111010001

011  
111  
110  
101  
010  
100  
000

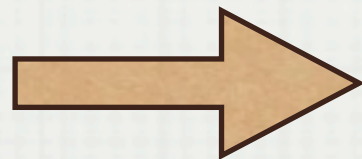


# EXAMPLE

A MINIMUM-LENGTH BINARY STRING THAT CONTAINS AS A SUBSTRING  
EVERY BINARY STRING OF A PRESCRIBED LENGTH 3.

◆ 0111010001

011  
111  
110  
101  
010  
100  
000  
001





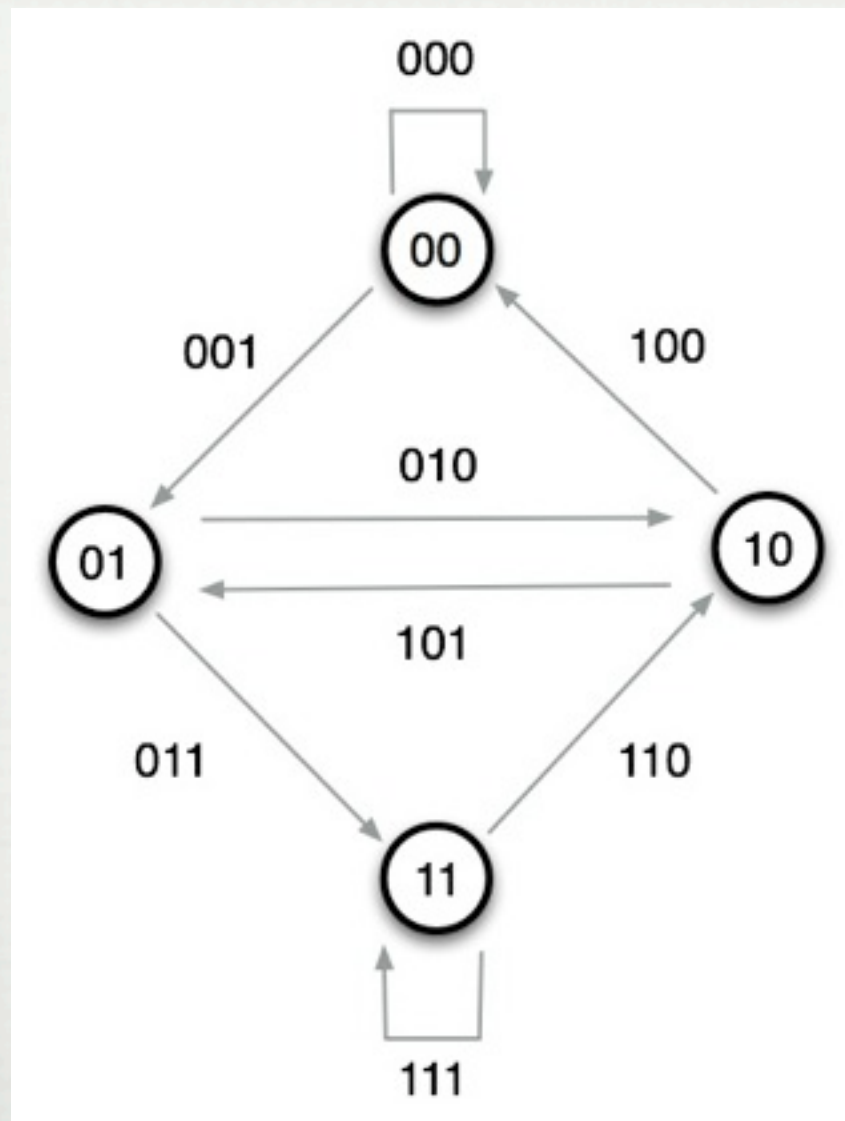
# THE DEBRUIJN DIAGRAM

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**Definition:** A deBruijn graph of order  $k$ , denoted by  $G(k)$ , is a directed graph with  $2^k$  vertices, each labeled with a unique  $k$ -bit string. Vertex  $a$  is joined to vertex  $b$  if bitstring  $b$  is obtainable from bitstring  $a$  by either a cycle shift or a deBruijn shift.

# EXAMPLE

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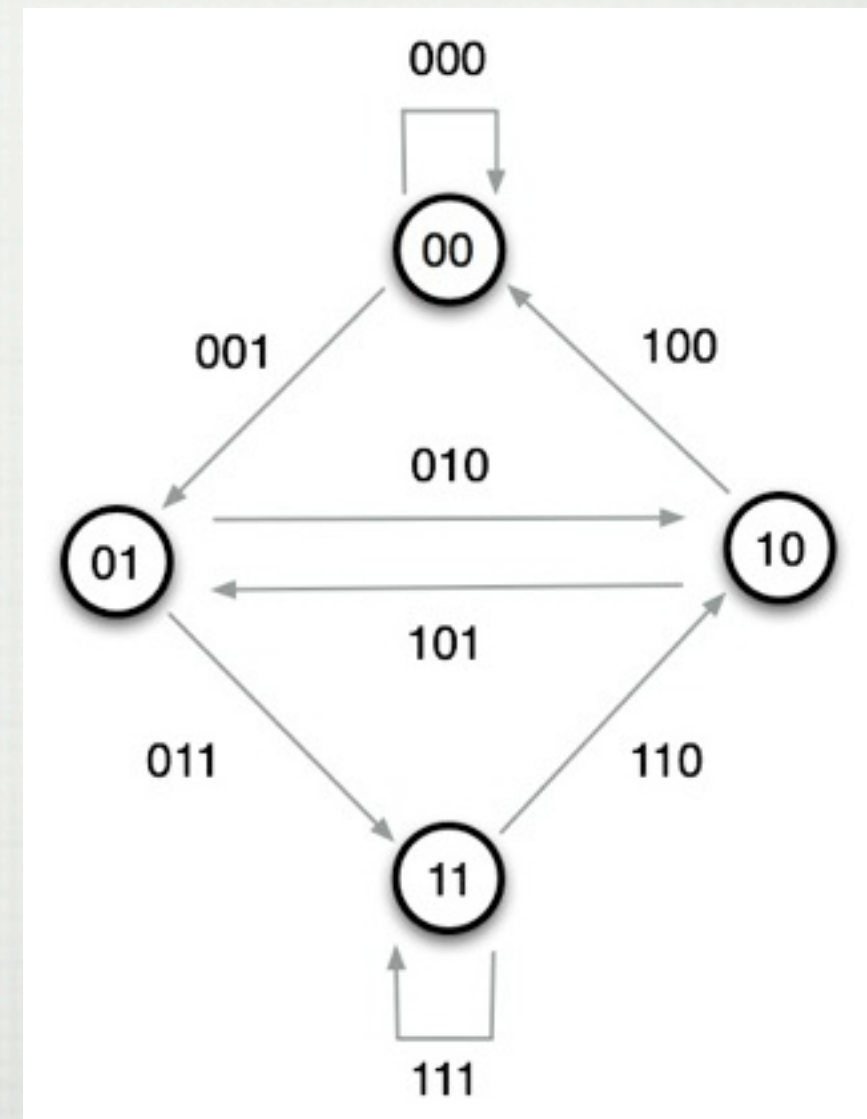




# THE DEBRUIJIN GRAPH

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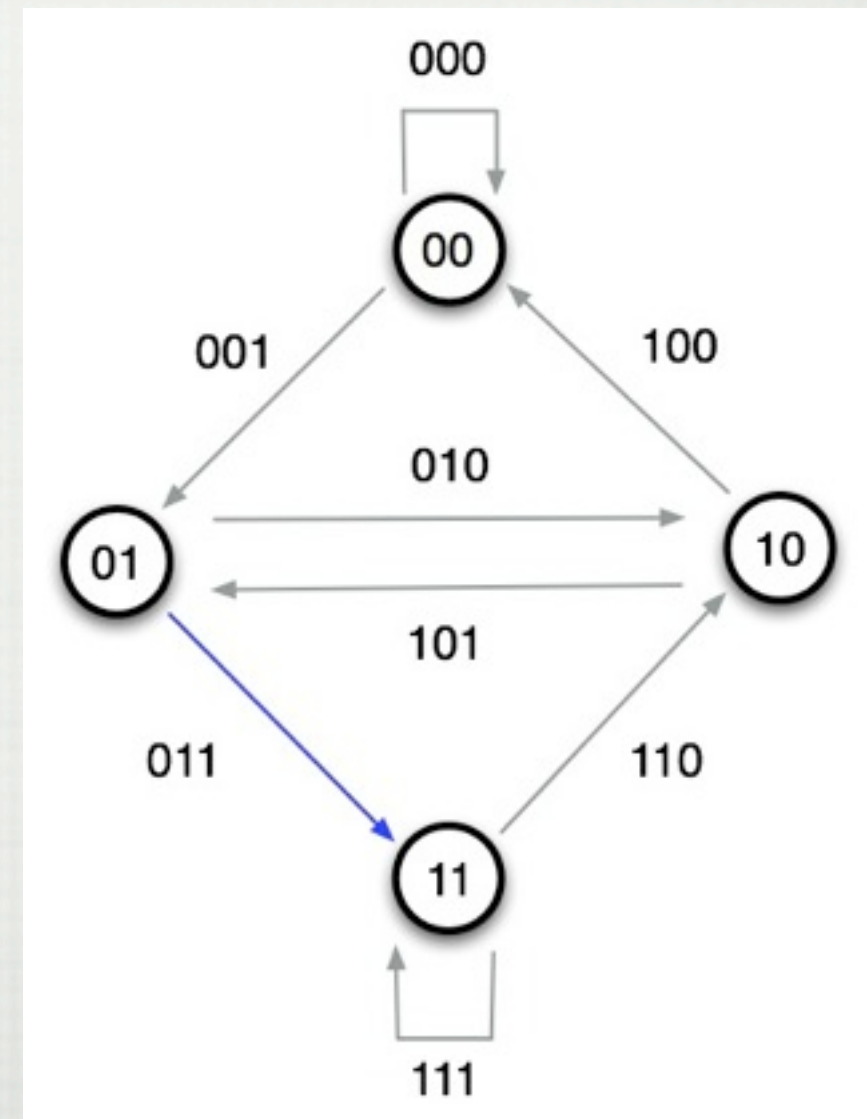
EULERIAN PATH  
THROUGH THE DEBRUIJIN  
GRAPH SOLVED THE  
PROBLEM



# THE DEBRUIJIN GRAPH

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EULERIAN PATH  
THROUGH THE DEBRUIJIN  
GRAPH SOLVED THE  
PROBLEM



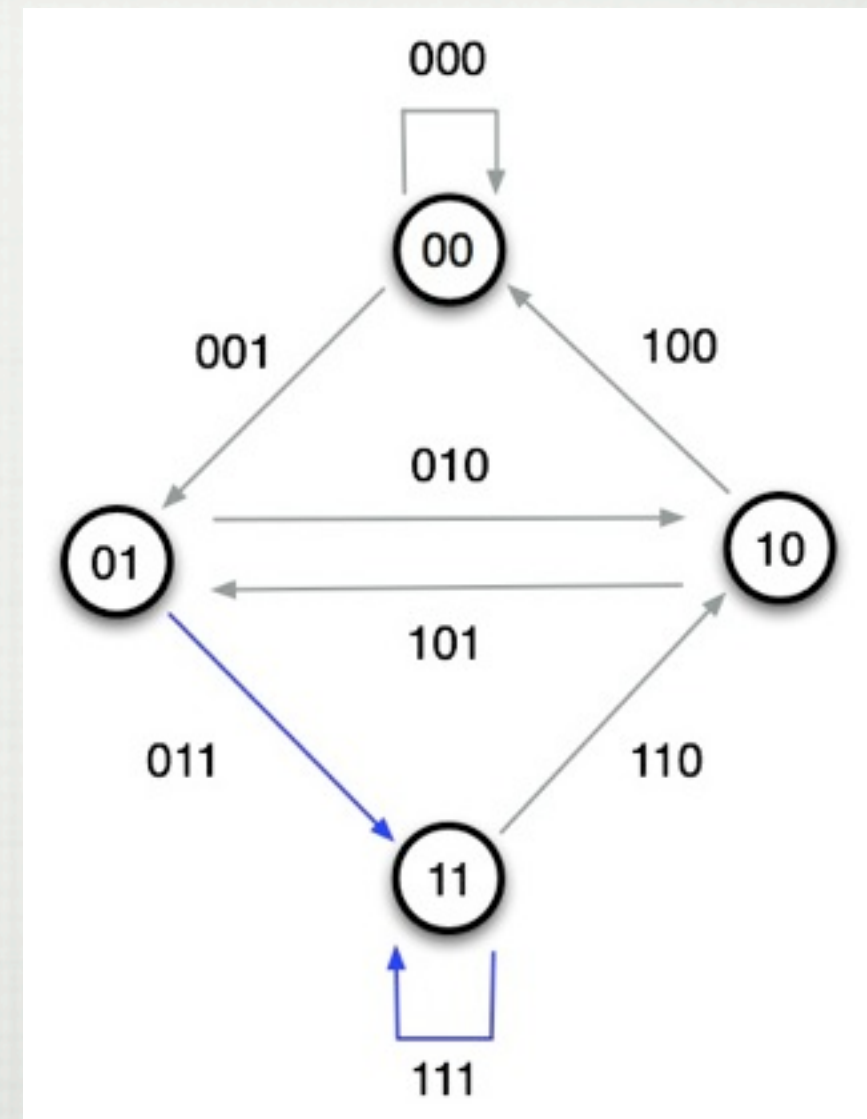
011



# THE DEBRUIJIN GRAPH

---

EULERIAN PATH  
THROUGH THE DEBRUIJIN  
GRAPH SOLVED THE  
PROBLEM

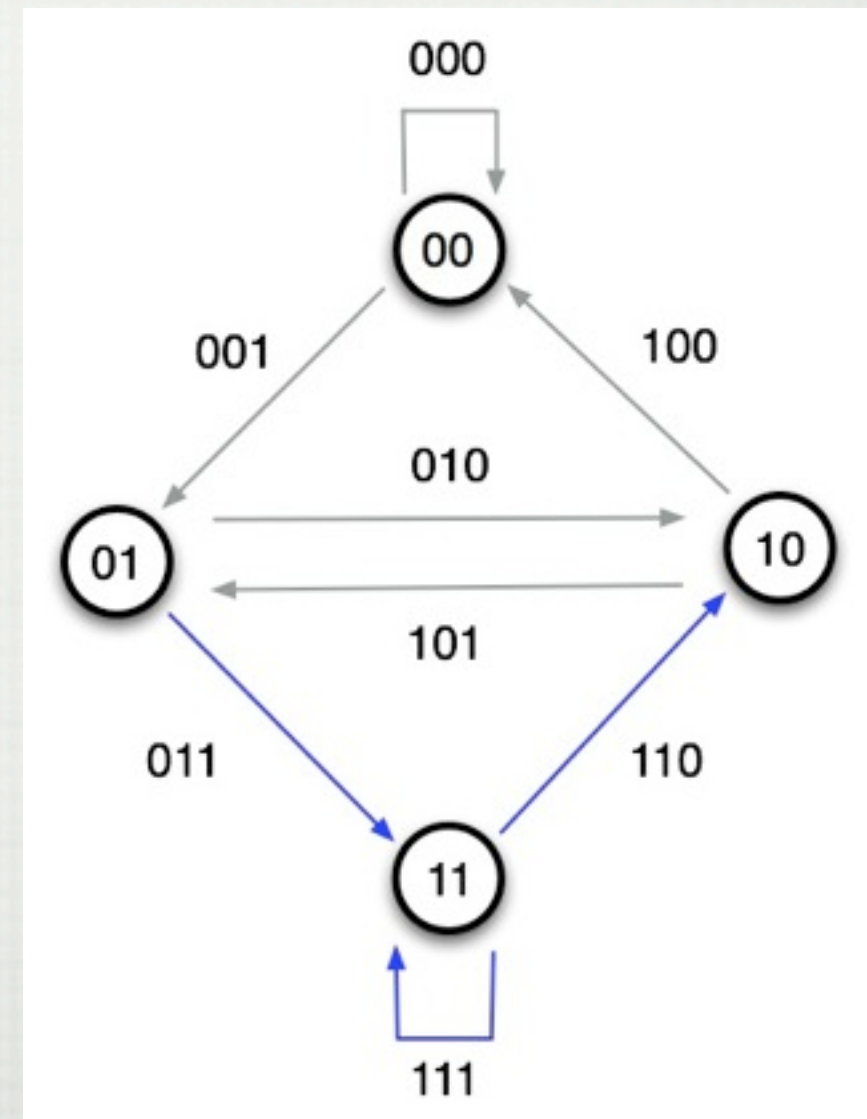


0111

# THE DEBRUIJIN GRAPH

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EULERIAN PATH  
THROUGH THE DEBRUIJIN  
GRAPH SOLVED THE  
PROBLEM



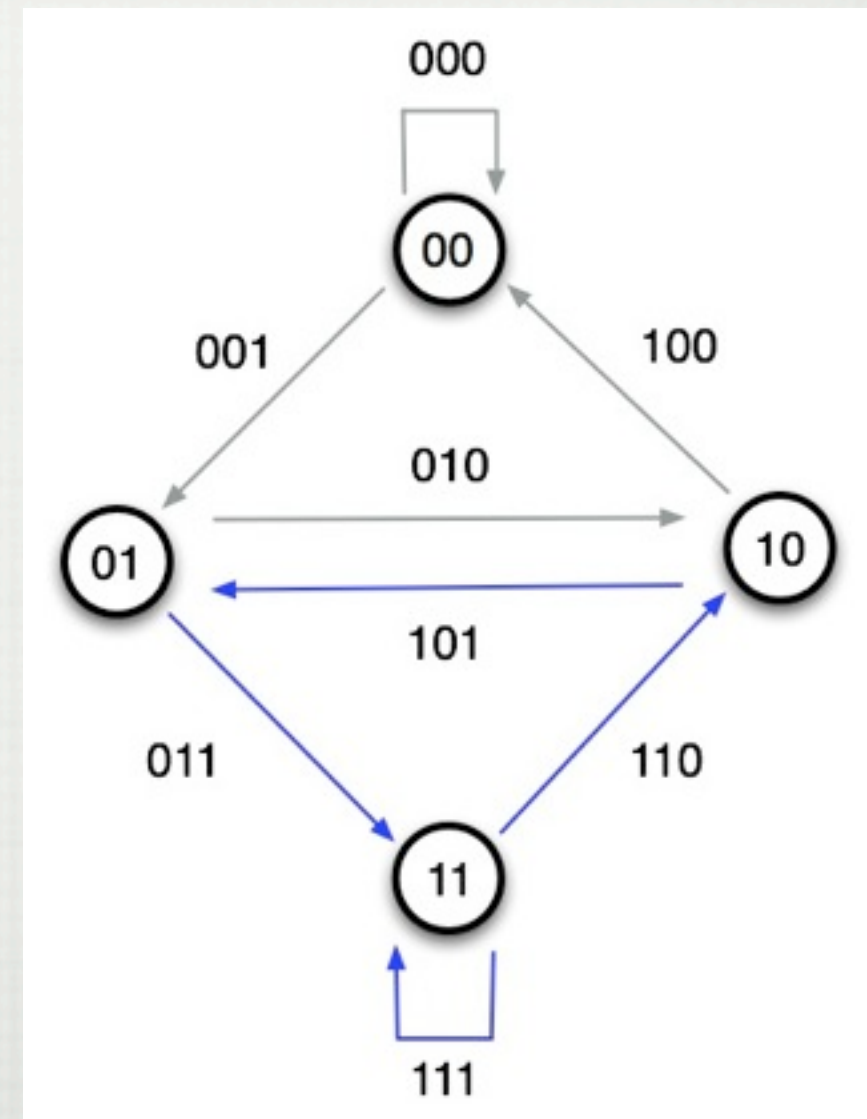
01110



# THE DEBRUIJIN GRAPH

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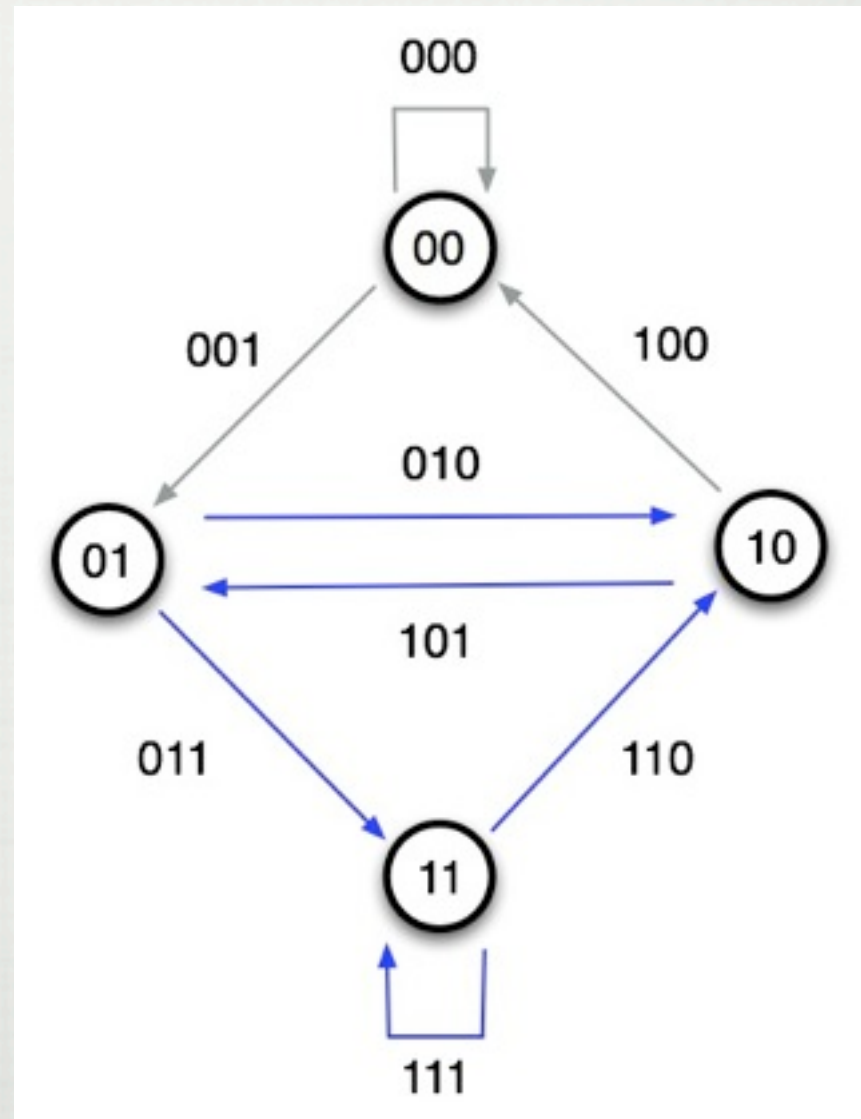
EULERIAN PATH  
THROUGH THE DEBRUIJIN  
GRAPH SOLVED THE  
PROBLEM



011101

# THE DEBRUIJIN GRAPH

EULERIAN PATH  
THROUGH THE DEBRUJIN  
GRAPH SOLVED THE  
PROBLEM



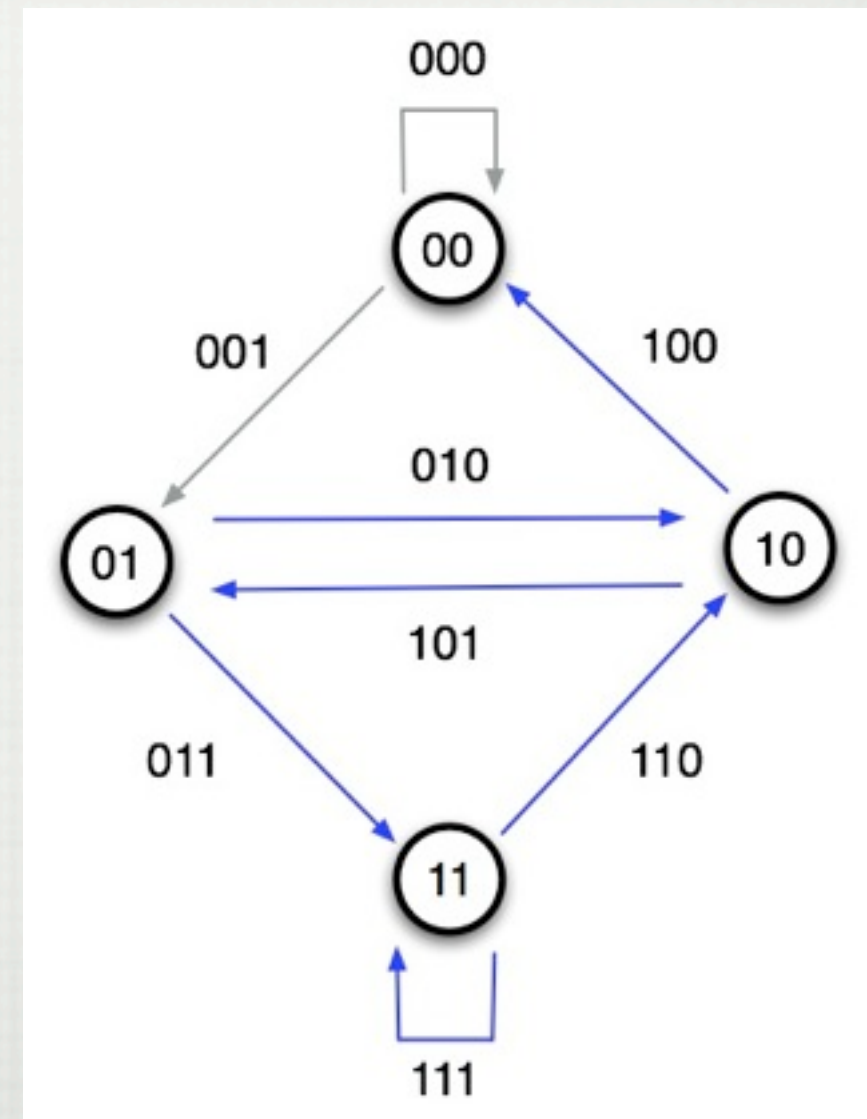
0111010



# THE DEBRUIJIN GRAPH

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EULERIAN PATH  
THROUGH THE DEBRUIJIN  
GRAPH SOLVED THE  
PROBLEM

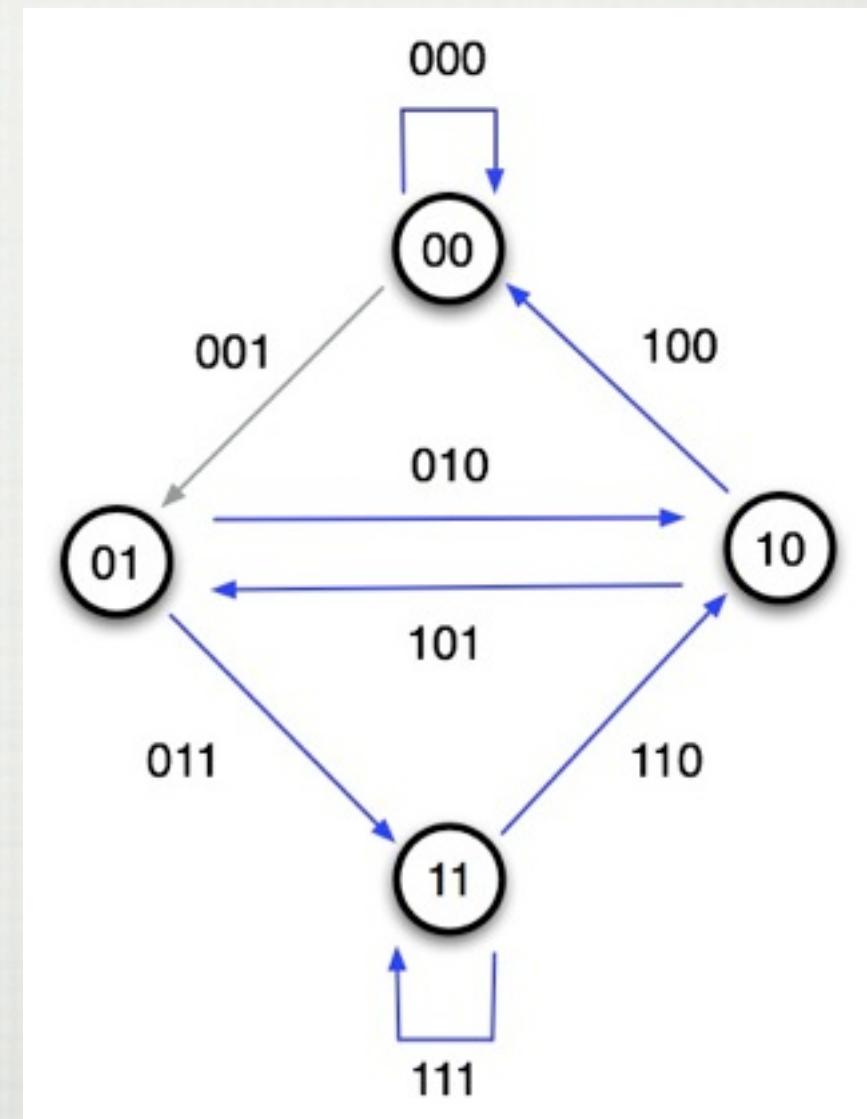


01110100

# THE DEBRUIJIN GRAPH

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EULERIAN PATH  
THROUGH THE DEBRUIJIN  
GRAPH SOLVED THE  
PROBLEM



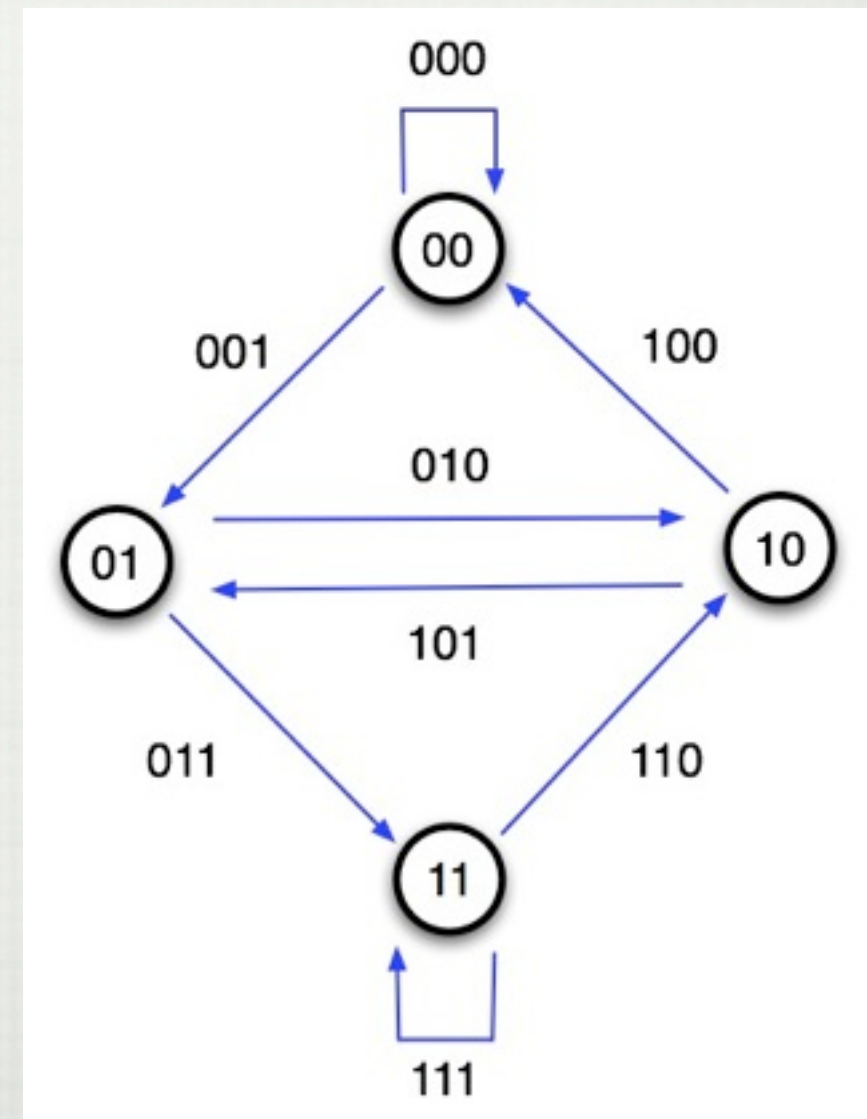
011101000



# THE DEBRUIJIN GRAPH

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EULERIAN PATH  
THROUGH THE DEBRUIJIN  
GRAPH SOLVED THE  
PROBLEM



0111010001

# CELLULAR AUTOMATA

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A one-dimensional cellular automaton is a discrete dynamical system it consist in a quintuple,  $\{\Sigma, \Phi, \varphi, \eta_r(x_i), c_0\}$ , wherein:

- $\Sigma$  is a finite set of states, from which the configurations of  $c$  cells take their values,  $c : \mathbb{Z} \rightarrow \Sigma$ .
- $\eta_r(x_i) = x_{i-r}, \dots, x_i, \dots, x_{i+r}$  is the neighborhood of  $x_i$  of radius  $r$ , whose size is  $\tau = |\eta_r(x_i)|$ .
- $\varphi : \Sigma^\tau \rightarrow \Sigma$ , a local function which maps neighborhoods with size  $\tau$  to a set of states  $\Sigma$ .
- $C_0$ , an initial configuration which is the starting point of the evolution.
- $\Phi$  is a global function that computes transformations between sets of configurations.



# EXAMPLE

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$$\Sigma = \{ \square, \blacksquare \}$$

$$r = 1$$



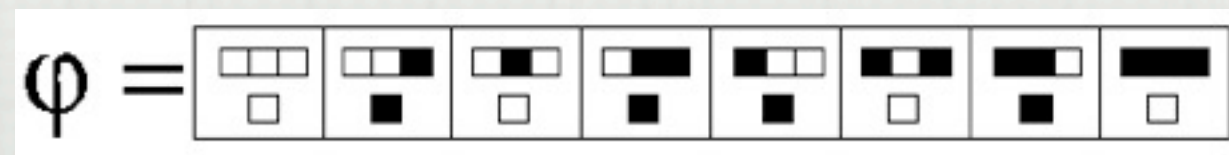
$$\varphi =$$

<div style="display: flex; justify-content: space-around;"><div>□</div><div>□</div><div>□</div></div> <div style="text-align: center;">□</div>	<div style="display: flex; justify-content: space-around;"><div>□</div><div>□</div><div>■</div></div> <div style="text-align: center;">■</div>	<div style="display: flex; justify-content: space-around;"><div>□</div><div>■</div><div>□</div></div> <div style="text-align: center;">□</div>	<div style="display: flex; justify-content: space-around;"><div>□</div><div>■</div><div>■</div></div> <div style="text-align: center;">■</div>	<div style="display: flex; justify-content: space-around;"><div>■</div><div>□</div><div>□</div></div> <div style="text-align: center;">■</div>	<div style="display: flex; justify-content: space-around;"><div>■</div><div>□</div><div>■</div></div> <div style="text-align: center;">□</div>	<div style="display: flex; justify-content: space-around;"><div>■</div><div>■</div><div>□</div></div> <div style="text-align: center;">■</div>	<div style="display: flex; justify-content: space-around;"><div>■</div><div>■</div><div>■</div></div> <div style="text-align: center;">□</div>
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## EXAMPLE

$$\Sigma = \{ \square, \blacksquare \}$$

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## EXAMPLE

$$\Sigma = \{ \square, \blacksquare \}$$

$$r = 1$$



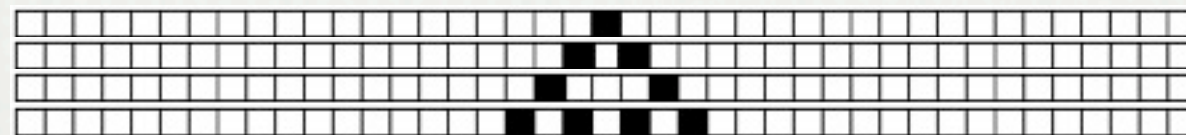
[illegible]

# EXAMPLE

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$$\Sigma = \{ \square, \blacksquare \}$$

$$r = 1$$



$$\varphi =$$

<div style="display: flex; justify-content: space-around;"><div>□</div><div>□</div><div>□</div></div> <div style="text-align: center;">□</div>	<div style="display: flex; justify-content: space-around;"><div>□</div><div>□</div><div>■</div></div> <div style="text-align: center;">■</div>	<div style="display: flex; justify-content: space-around;"><div>□</div><div>■</div><div>□</div></div> <div style="text-align: center;">□</div>	<div style="display: flex; justify-content: space-around;"><div>□</div><div>■</div><div>■</div></div> <div style="text-align: center;">■</div>	<div style="display: flex; justify-content: space-around;"><div>■</div><div>□</div><div>□</div></div> <div style="text-align: center;">■</div>	<div style="display: flex; justify-content: space-around;"><div>■</div><div>□</div><div>■</div></div> <div style="text-align: center;">□</div>	<div style="display: flex; justify-content: space-around;"><div>■</div><div>■</div><div>□</div></div> <div style="text-align: center;">■</div>	<div style="display: flex; justify-content: space-around;"><div>■</div><div>■</div><div>■</div></div> <div style="text-align: center;">□</div>
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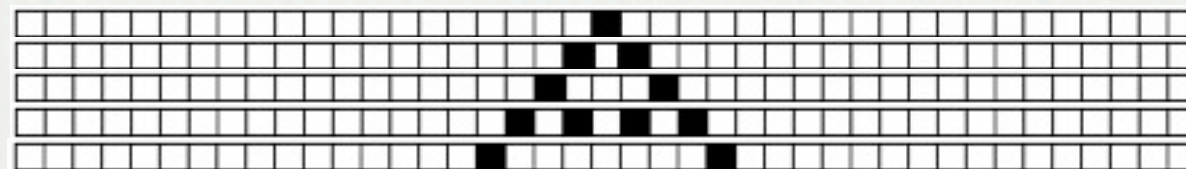


# EXAMPLE

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$$\Sigma = \{ \square, \blacksquare \}$$

$$r = 1$$

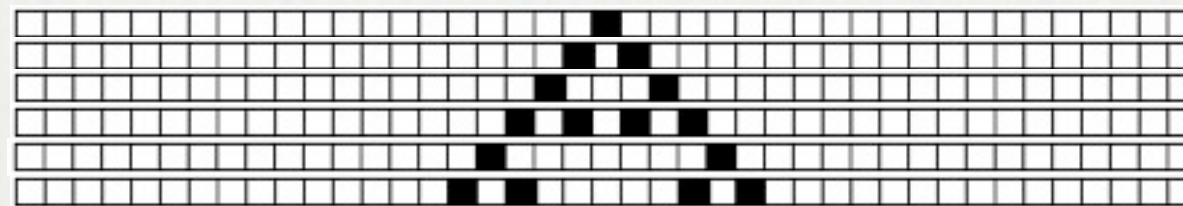


$$\varphi = \begin{array}{|c|c|c|c|c|c|c|c|} \hline \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \square & & \end{array} & \begin{array}{|c|c|c|} \hline \square & \blacksquare & \blacksquare \\ \hline \blacksquare & & \end{array} & \begin{array}{|c|c|c|} \hline \square & \blacksquare & \square \\ \hline \square & & \end{array} & \begin{array}{|c|c|c|} \hline \square & \blacksquare & \blacksquare \\ \hline \blacksquare & & \end{array} & \begin{array}{|c|c|c|} \hline \blacksquare & \square & \square \\ \hline \blacksquare & & \end{array} & \begin{array}{|c|c|c|} \hline \blacksquare & \square & \blacksquare \\ \hline \square & & \end{array} & \begin{array}{|c|c|c|} \hline \blacksquare & \blacksquare & \square \\ \hline \blacksquare & & \end{array} & \begin{array}{|c|c|c|} \hline \blacksquare & \blacksquare & \blacksquare \\ \hline \square & & \end{array} \\ \hline \end{array}$$

## EXAMPLE

$$\Sigma = \{ \square, \blacksquare \}$$

$$r = 1$$



[illegible]

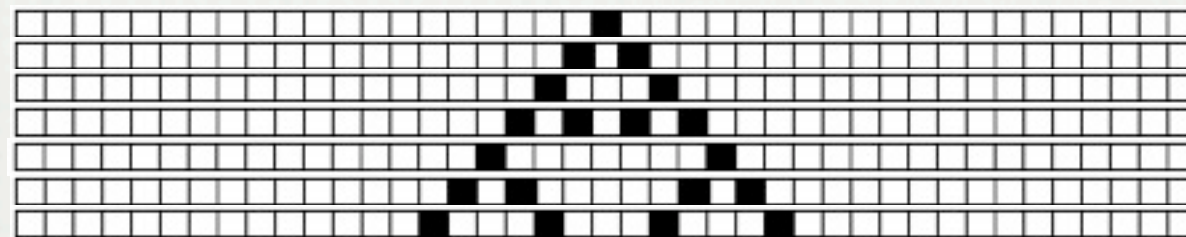


# EXAMPLE

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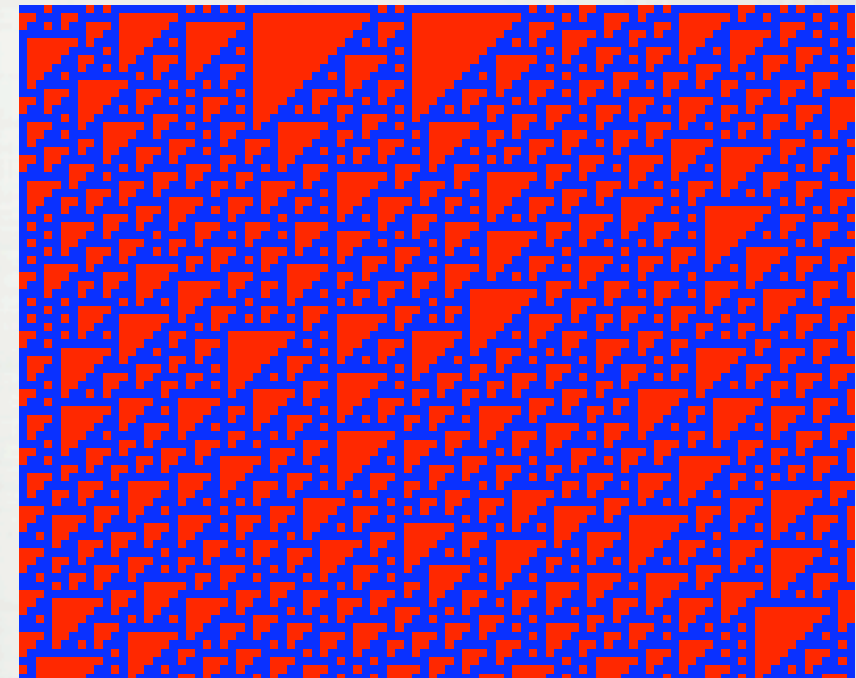
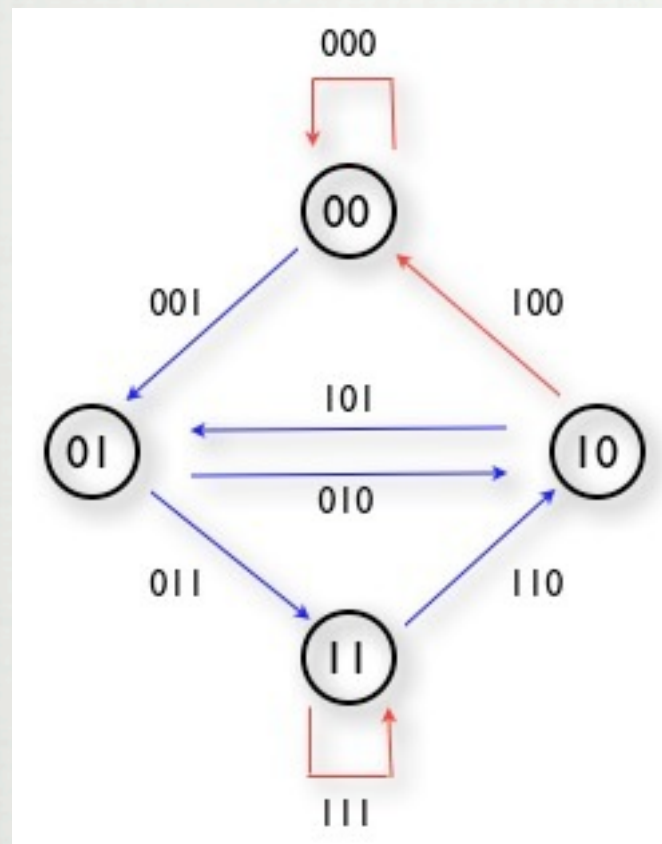
$$\Sigma = \{ \square, \blacksquare \}$$

$$r = 1$$



$$\varphi = \begin{bmatrix} \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \square & & \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \square & \square & \blacksquare \\ \hline \square & & \blacksquare \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \square & \blacksquare & \square \\ \hline \square & & \square \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \square & \blacksquare & \blacksquare \\ \hline \square & & \blacksquare \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \blacksquare & \square & \square \\ \hline \blacksquare & & \square \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \blacksquare & \square & \blacksquare \\ \hline \blacksquare & & \square \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \blacksquare & \blacksquare & \square \\ \hline \blacksquare & & \square \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \blacksquare & \blacksquare & \blacksquare \\ \hline \blacksquare & & \square \\ \hline \end{array} \end{bmatrix}$$

# THE DEBRUIJIN DIAGRAM AND CELLULAR AUTOMATA



$$\varphi = \{ 000, 100, 111 \rightarrow 0, 001, 010, 011, 101, 110 \rightarrow 1 \}$$

■  $\Rightarrow$  0

■  $\Rightarrow$  1



# PREIMAGES

---

The preimages of a single cell are the locally valid neighborhoods defined by the inverse of the local transition function

$$\varphi^{-1}(c_x^t) = \{n_x^t - 1 \in \Sigma^N \mid \varphi(n_x^{t-1} = c_v^t)\}$$

Preimages  $C^{t-1}$  of a block  $m$  are defined by the inverse of the local transition function

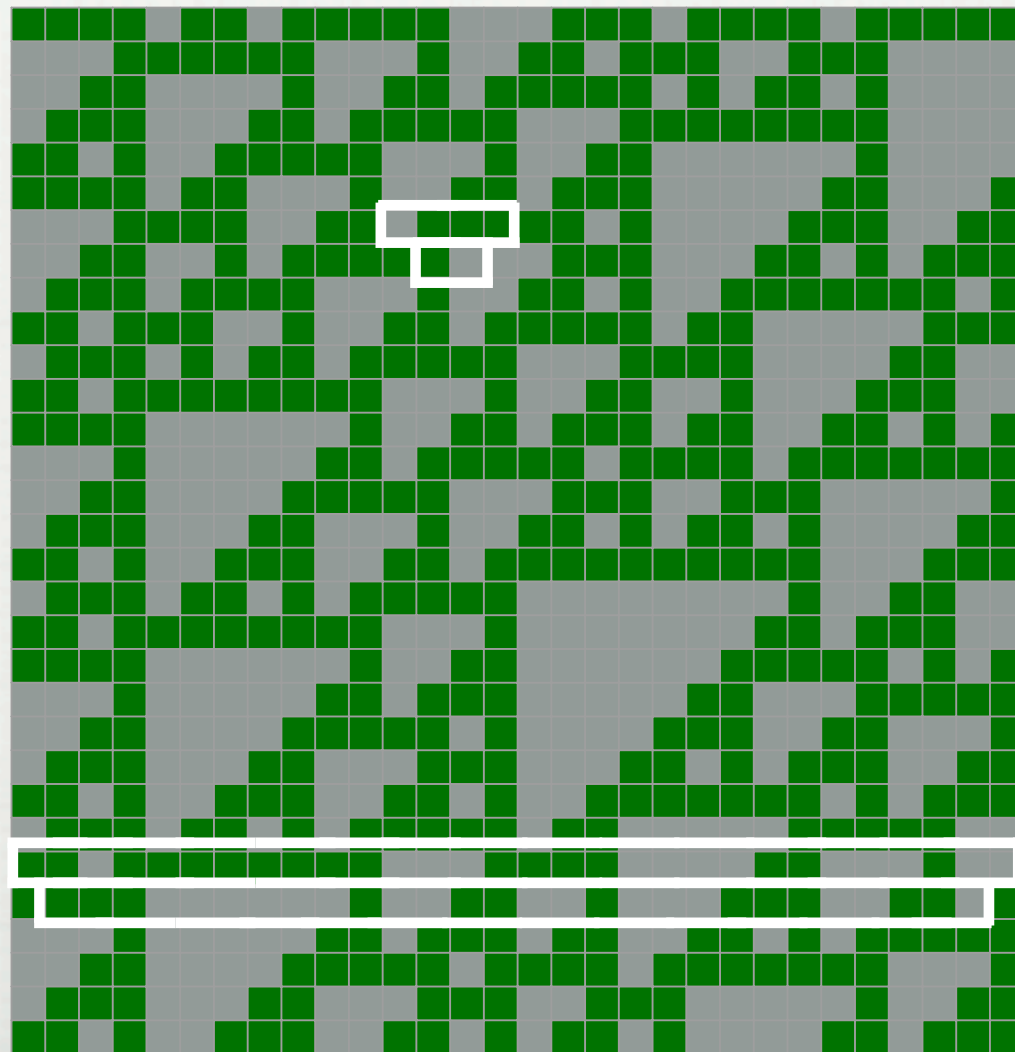
$$\varphi^{-1}(c_x^t) = \{m_x^t - 1 \in \Sigma^N \mid \varphi(m_x^{t-1} = c_v^t)\}$$

Locally valid neighborhoods of adjacent cells must overlap correctly to become  $m$  block valid.

# EXAMPLE OF PREIMAGE

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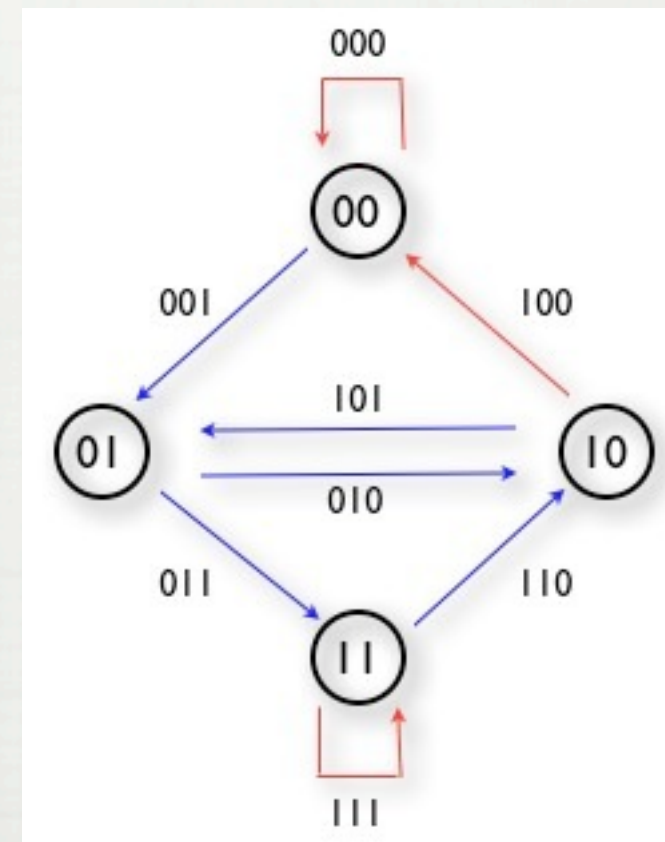
■ → 0  
■ → 1





# PREIMAGES AND THE BRUIJIN GRAPH

LABELING EDGES  
AS  
NEIGHBORHOODS  
AND AS  
NEIGHBORHOODS  
MAPPING



0111  
10

■ → 0  
■ → 1

# MATRIX REPRESENTATION OF THE DEBRUIJIN GRAPH

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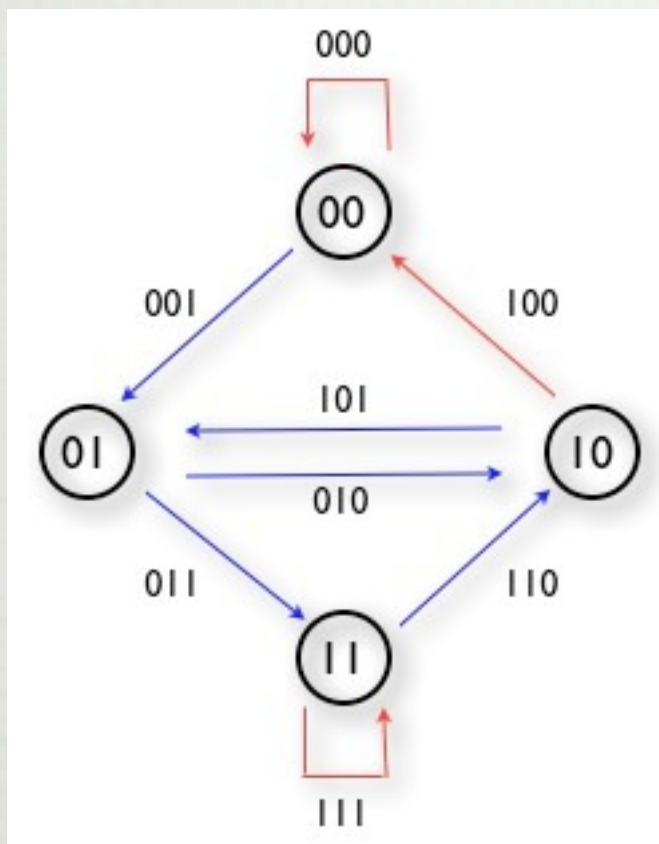
Let  $v_i$  and  $v_j \in V(G)$  of the *De Bruijn diagram* for  $i, j = 1, 2, 3, \dots, |V(G)|$ . The preimages matrix  $M(s)_{i,j}$  of state  $s \in \Sigma$  is defined as:

$$M(s)_{i,j} = \begin{cases} \{N(v_i v_j)\} & \text{If } \phi(N(v_i, v_j)) = s \text{ where } s \in \Sigma \\ \emptyset & \text{elsewhere} \end{cases} \quad (1)$$

where its element sets are neighborhood that represent  $v_i$  and  $v_j$  for  $i, j = 1 \dots |V(G)|$  it means  $N(v_i, v_j)$ , where the mapping corresponds to state  $s \in \Sigma$ . To simplify the notation  $M(s)_{i,j}$  is denoted as  $M_s$ .



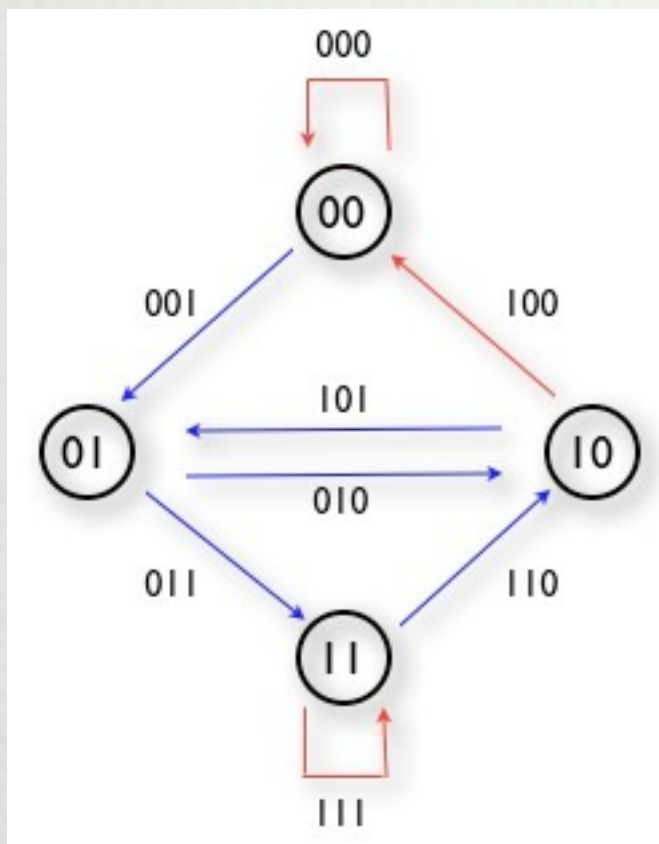
# PREIMAGES MATRIX STATE 0



$$M_0 = \begin{pmatrix} \{ \text{"000"} \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ \text{"100"} \} & \emptyset & - & - \\ - & - & \emptyset & \{ \text{"111"} \} \end{pmatrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1

# PREIMAGES MATRIX STATE 0

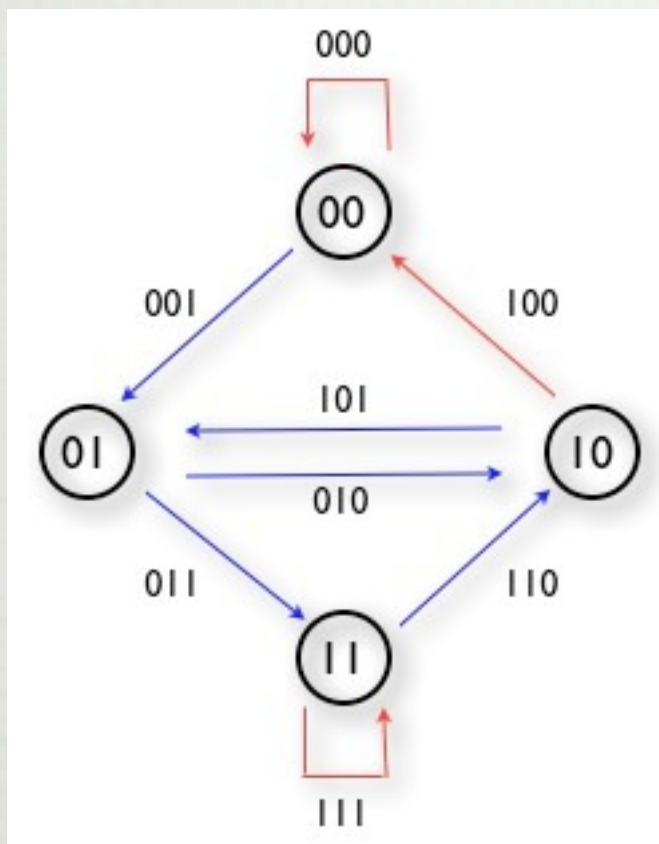


$$M_0 = \begin{matrix} & 00 \\ \begin{pmatrix} \{ \text{"000"} \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ \text{"100"} \} & \emptyset & - & - \\ - & - & \emptyset & \{ \text{"111"} \} \end{pmatrix} \end{matrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1



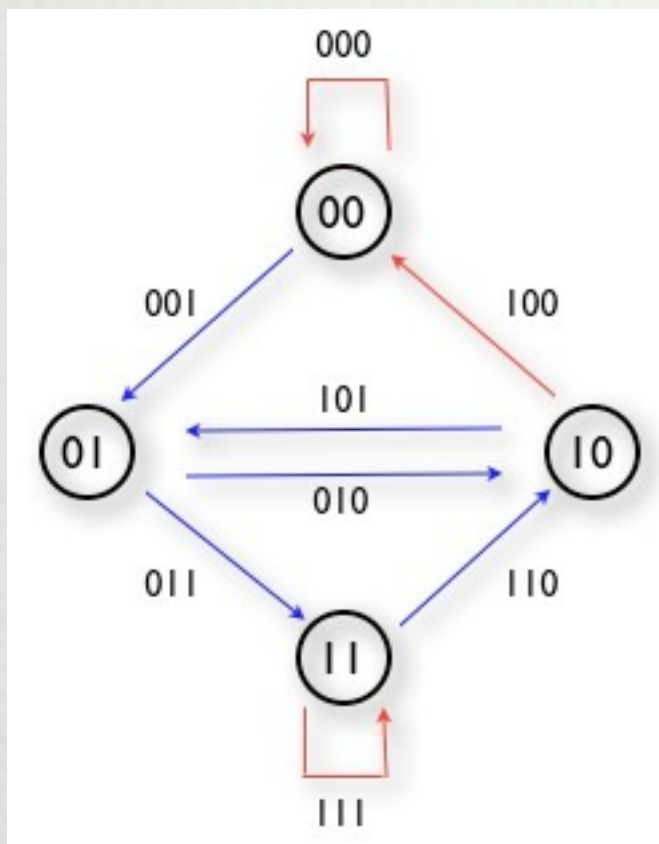
# PREIMAGES MATRIX STATE 0



$$M_0 = \begin{pmatrix} \begin{matrix} 00 & 01 \end{matrix} \\ \begin{matrix} \{ "000" \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ "100" \} & \emptyset & - & - \\ - & - & \emptyset & \{ "111" \} \end{matrix} \end{pmatrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1

# PREIMAGES MATRIX STATE 0

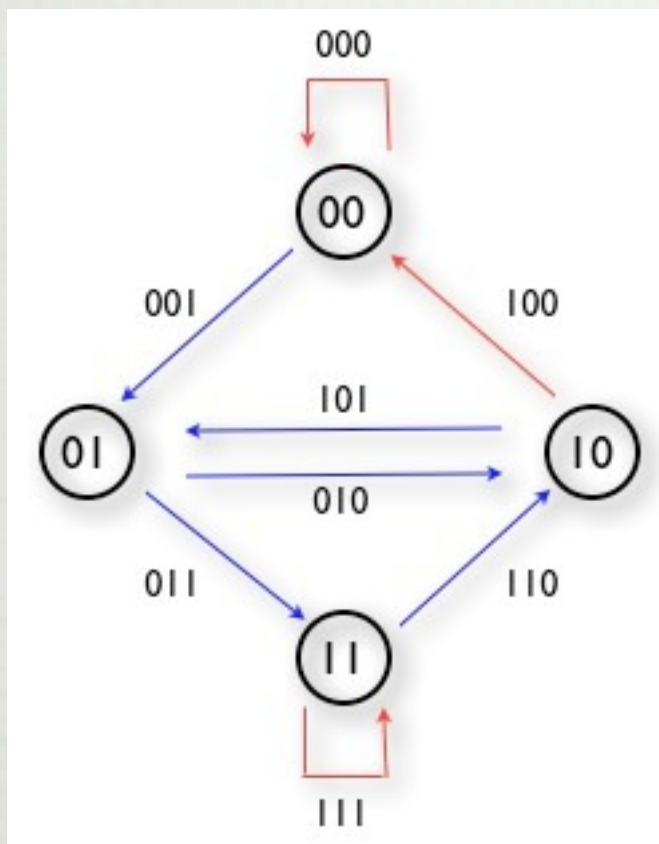


$$M_0 = \begin{matrix} & \begin{matrix} 00 & 01 & 10 \end{matrix} \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{pmatrix} \{ \text{"000"} \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ \text{"100"} \} & \emptyset & - & - \\ - & - & \emptyset & \{ \text{"111"} \} \end{pmatrix} \end{matrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1



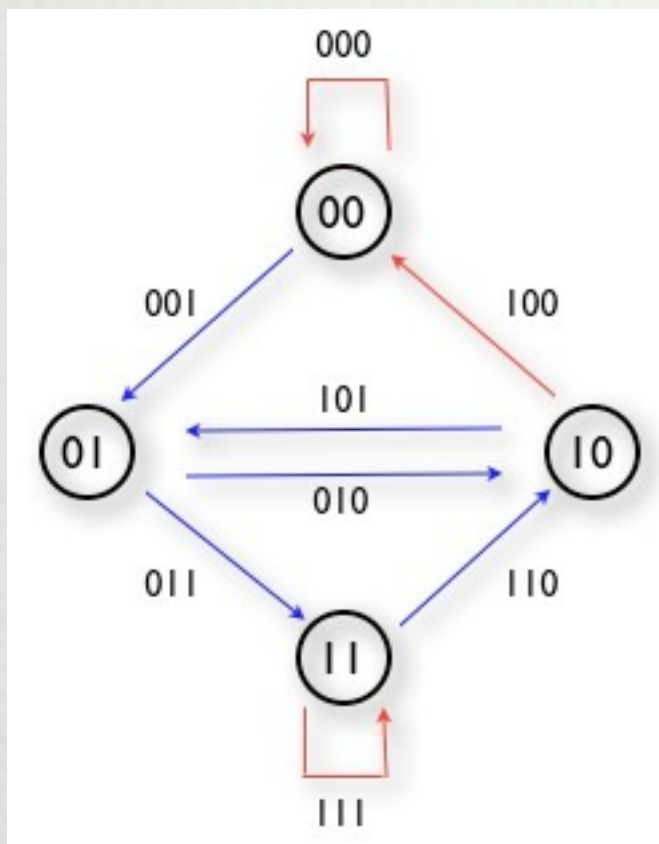
# PREIMAGES MATRIX STATE 0



$$M_0 = \begin{pmatrix} \begin{matrix} 00 & 01 & 10 & 11 \end{matrix} \\ \begin{matrix} \{ \text{"000"} \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ \text{"100"} \} & \emptyset & - & - \\ - & - & \emptyset & \{ \text{"111"} \} \end{matrix} \end{pmatrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1

# PREIMAGES MATRIX STATE 0

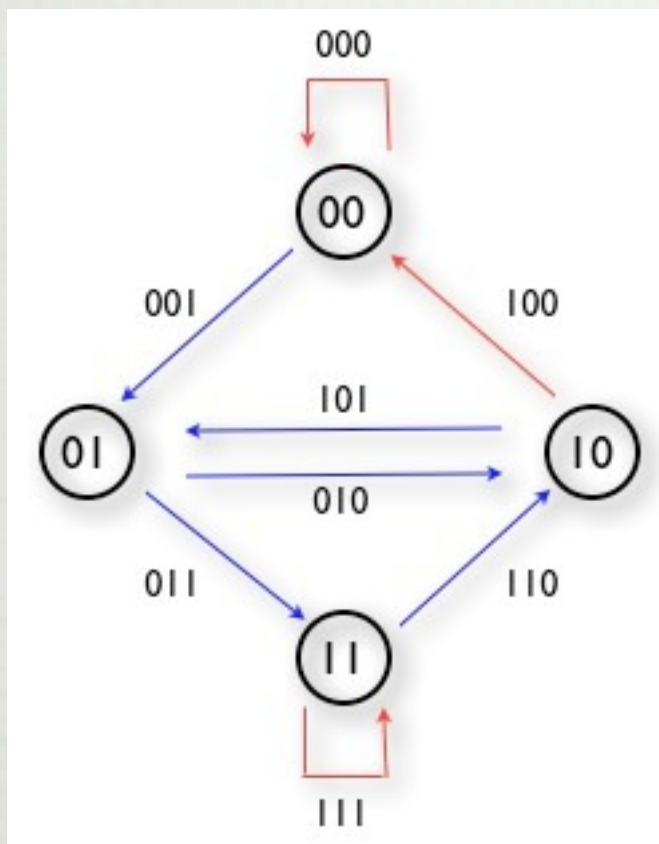


$$M_0 = \begin{matrix} & \begin{matrix} 00 & 01 & 10 & 11 \end{matrix} \\ \begin{matrix} 00 \end{matrix} & \left( \begin{array}{cccc} \{ \text{"000"} \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ \text{"100"} \} & \emptyset & - & - \\ - & - & \emptyset & \{ \text{"111"} \} \end{array} \right) \end{matrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1



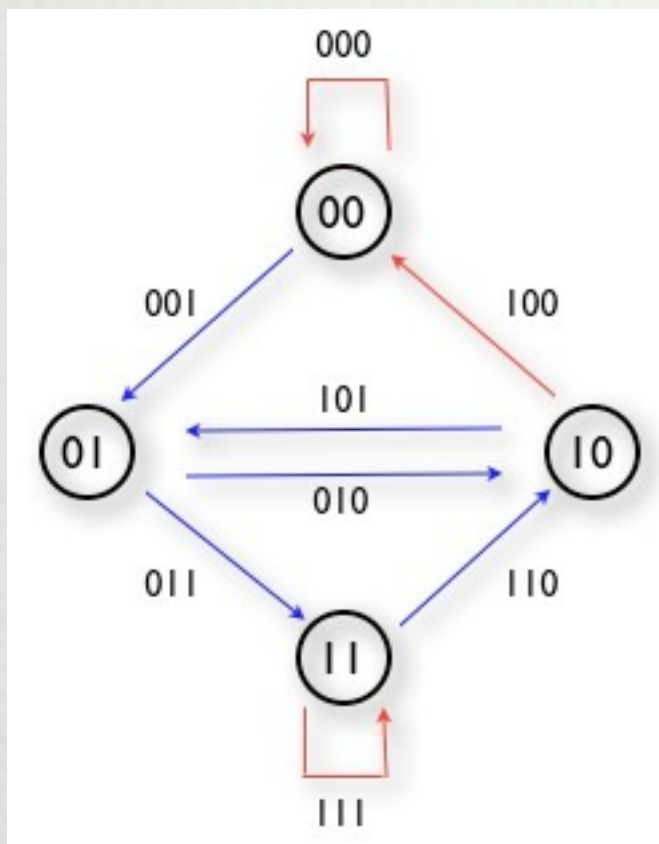
# PREIMAGES MATRIX STATE 0



$$M_0 = \begin{matrix} & \begin{matrix} 00 & 01 & 10 & 11 \end{matrix} \\ \begin{matrix} 00 \\ 01 \end{matrix} & \left( \begin{array}{cccc} \{ "000" \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ "100" \} & \emptyset & - & - \\ - & - & \emptyset & \{ "111" \} \end{array} \right) \end{matrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1

# PREIMAGES MATRIX STATE 0

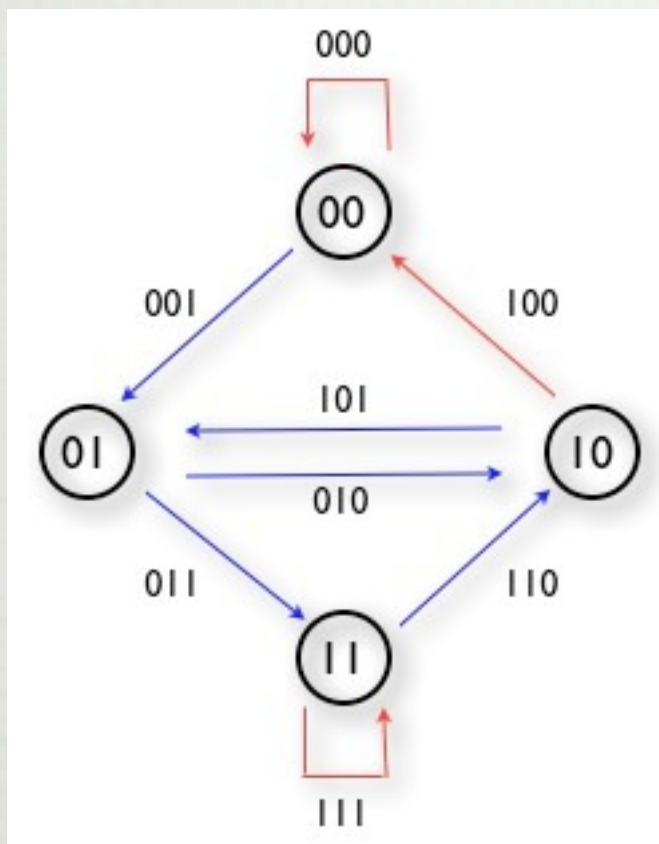


$$M_0 = \begin{matrix} & \begin{matrix} 00 & 01 & 10 & 11 \end{matrix} \\ \begin{matrix} 00 \\ 01 \\ 10 \end{matrix} & \left( \begin{array}{cccc} \{ \text{"000"} \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ \text{"100"} \} & \emptyset & - & - \\ - & - & \emptyset & \{ \text{"111"} \} \end{array} \right) \end{matrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1



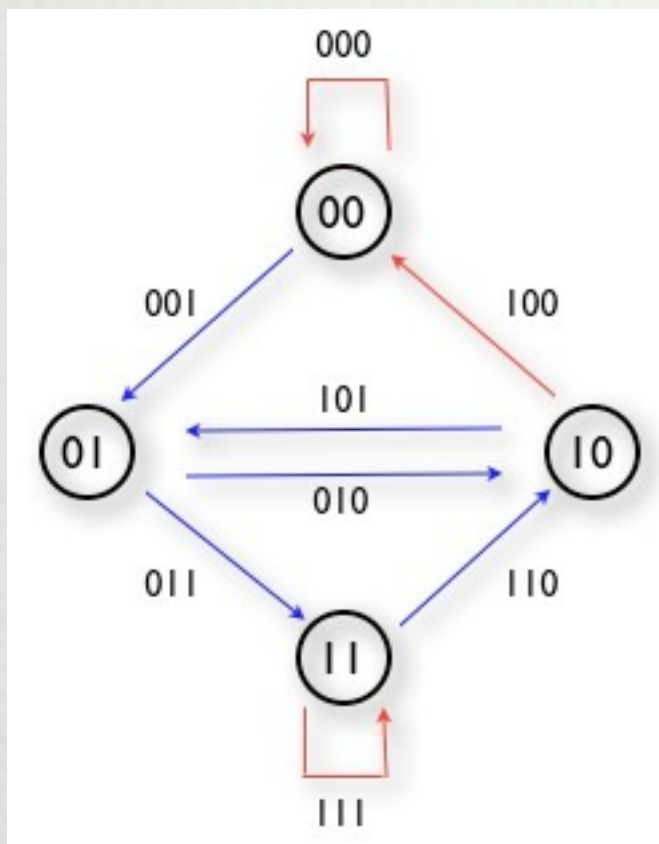
# PREIMAGES MATRIX STATE 0



$$M_0 = \begin{matrix} & \begin{matrix} 00 & 01 & 10 & 11 \end{matrix} \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \left( \begin{array}{cccc} \{ \text{"000"} \} & \emptyset & - & - \\ - & - & \emptyset & \emptyset \\ \{ \text{"100"} \} & \emptyset & - & - \\ - & - & \emptyset & \{ \text{"111"} \} \end{array} \right) \end{matrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1

# PREIMAGES MATRIX STATE I



$$M_1 = \begin{matrix} & \begin{matrix} 00 & 01 & 10 & 11 \end{matrix} \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \left( \begin{array}{cccc} \emptyset & \{ "001" \} & - & - \\ - & - & \{ "010" \} & \{ "011" \} \\ \emptyset & \{ "101" \} & - & - \\ - & - & \{ "110" \} & \emptyset \end{array} \right) \end{matrix}$$

■  $\Rightarrow$  0  
■  $\Rightarrow$  1



# OPERATOR BETWEEN MATRICES TO CALCULATE PREIMAGES

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